On solving linear Fredholm integro-differential equations via finite difference-Simpson’s approach

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Abstract
In this paper, a combination of Finite difference-Simpson’s approach were applied to solve Linear Fredholm integro-differential equations of second kind by discritising the unknown function, which leads in generating a system of linear algebraic equations. The numerical results obtained from the proposed method were compared with exact solutions of the tested problems which show that the method derived is effective and promising when compared with some existing method in the literature and error estimation of the scheme was derived.

Keywords
Error estimation, Finite difference equations, Fredholm integro-differential equation, Simpson’s Method.

AMS Subject Classification
45A05, 45B05, 45J05, 45P05.

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Contents
1 Introduction .................................................. 469
2 Derivation of the Method .............................. 470
3 Error Estimation .......................................... 470
4 Numerical Examples ................................. 471
5 Conclusion ................................................. 471
References ....................................................... 472

1. Introduction
Mathematical modeling of real life problems often result in functional equations such as differential, integral and integro-differential equations. Many mathematical formualtion of physical phenomena reduced to integro-differential equations like Fluid dynamics, Biological models and chemical kinetics [7, 14, 15].

In general, the exact solution of integro-differential equations is difficult to obtain. Therefore, that is why there have been a great attention by many researchers on how to obtain an approximate solution of integro-differential equations of different kind such as [2, 4, 7, 8, 13]. Nevertheless these methods require more effort and usually they are meant for special types of integro-differential equation problems. We consider a Linear integro-differential equation of the form:

\[ u'(x) = f(x) + \lambda \int_a^b k(x,t)u(t)dt, \quad u_0 = \alpha. \]  

(1.1)

where \(a, b\) and \(\lambda\) are constants, \(f(x)\) and \(k(x,t)\) are known function with \(k(x,t)\) is the kernel and \(u\) is the unknown function to be determined.

Darania and Ebadian [2] studied first order linear Fredholm Integro-differential equations, a Differential transform based on Taylor’s series expansion has been successfully employed to obtained the approximate solution and provide applicable relation between the one and two dimensional transformation,numerical examples were given to show the effectiveness of the method. According to Danfu. H and Xufeng. [4] used a cos and sine (CAS) wavelet operational matrix of integration method was used to reduce IDEs into a system of linear equations. Numerical results showed that CAS wavelet method is better than a Differential Transform method.

Vahidi et.al [8] applied Adomian’s decomposition method (ADM) and comparison was made with two different Numerical methods; CAS wavelet and Differential Transform, which showed that ADM gave a better approximation and is more efficient.

Tamamagar M. [13] obtained numerical solution of linear Fredholm integro-differential equations via Parametric
iteration method (PIM), some examples were considered and convergence analysis was studied.

Moreover, In this paper we propose a Finite difference-Simpson’s approach to solve equation (1.1) by transforming the equation into a system of linear equations. Comparison were made with exact solution and two different methods presented in the literature. The remainder of the paper is organized as follows: In Section 2, we presented the derivation of the method. Error estimation of the scheme was proved in section 3, and numerical results were provided in section 4. Section 5 gives the conclusion.

2. Derivation of the Method

We defined N finite points of the domain \( [a, b] \) of (1.1) as \( a = t_0 < t_1 < \ldots < t_{N-1} < t_N = b \) using uniform step length \( h = \frac{b-a}{N} \), such that \( x_i = a + ih, \quad i = 1, 2, \ldots, N. \)

To obtain numerical solution, we use Finite difference on the differential part and composite Simpson’s on the integral part of (1.1). Now using Composite Simpson’s with N subintervals and \( t \in [a, b] \), the integral part of (1.1) is approximated by

\[
\int_a^b k(x, t)u(t)dt \approx \frac{h}{3}[k(x,t_0)u(t_0) + 4k(x,t_1)u(t_1) + \ldots + 4k(x,t_{N-1})u(t_{N-1}) + k(x,t_N)u(t_N)].
\]

By discretizing along \( x \) and taking \( u_i' = u_i'(x_i), \quad k(x_i,t_i) = k_{ij}, \) we have

\[
u_i' = f_i + \frac{h}{3}[k_{0i}u_0 + 4k_{i1}u_1 + 2k_{i2}u_2 + \ldots + 2k_{iN2}u_{N-2} + 4k_{iN-1}u_{N-1} + k_{iN}u_N], \tag{2.1}
\]

using Central difference we can approximate the derivative part of (2.1) as

\[
u_i' = \frac{u_{i+1} - u_{i-1}}{2h}, \quad i = 1, 2, \ldots, N - 1.
\]

and at the end point \( N \) we use second Backward Finite difference

\[
u_i' = \frac{3u_N - 4u_{N-1} + u_{N-2}}{2h}, \quad i = N,
\]

and by replacing \( u_i' \) in (2.1) we have

for \( i = 1, 2, \ldots, N - 1, \)

\[
u_i + u_{i-1} - u_{i-1} = \frac{f_i + \frac{h}{3}[k_{0i}u_0 + 4k_{i1}u_1 + 2k_{i2}u_2 + \ldots + 2k_{iN2}u_{N-2} + 4k_{iN-1}u_{N-1} + k_{iN}u_N]}{2h}, \tag{2.2}
\]

and for \( i = N \)

\[
\frac{3u_N - 4u_{N-1} + u_{N-2}}{2h} = f_N + \frac{h}{3}[k_{0N}u_0 + 4k_{N1}u_1 + 2k_{N2}u_2 + \ldots + 4k_{iN-1}u_{N-1} + k_{iN}u_N], \tag{2.3}
\]

using the above equations (2.2) and (2.3), we can generate a systems of equations for \( u_1, u_2, \ldots, u_N \) which can be represent in a matrix form

\[
MU = W
\]

and we define \( A_{ij} = -\frac{5}{3}h^2k_{ij}, \quad B_{ij} = -\frac{1}{2}h^2k_{ij}, \quad C_{ij} = -\frac{h^2}{2}k_{ij}. \)

3. Error Estimation

Theorem 3.1. Suppose that \( \mu_1, \mu_2, \mu_3 \in (a, b) \) such that the errors \( e_1 \) of central difference, \( e_2 \) of second backward difference approximation and \( e_3 \) of Simpson’s rule respectively are given by \( \frac{b^2}{6}u^{(3)}(\mu_1), \frac{b^2}{3}u^{(4)}(\mu_2) \) and \( \frac{(b-a)^2}{180}h^4u^{(4)}(\mu_2) \). Then the error estimation of approximate solution of linear Fredholm integro-differential equation (1.1) obtained by the scheme (2.2) and (2.3) is given by

\[
e \leq \frac{5(b-a)^2}{12N^2}G \tag{3.1}
\]

where \( G = \max\{u^3(\mu_1), u^4(\mu_2), u^4(\mu_3)\} \) and \( N \) is the number of subinterval.

Proof. From the problems of LFIDES (2.2) and (2.3), the exact solution after discretising for \( i = 1, 2, \ldots, N - 1, \)

\[
u_{i+1} + u_{i-1} - u_{i-1} = \frac{f_{i+1} + \frac{h}{3}[k_{0i}u_0 + \ldots + k_{iN}u_N]}{2h} + \frac{b-a}{180}h^4u^{(4)}(\mu_2), \tag{3.2}
\]
4. Numerical Examples

In this section, we presented some problems of linear Fredholm integro-differential equations and applied the proposed method of finite difference-Simpson’s approach to obtain the numerical solution, $N = 10$ was used in all the examples. The results obtained are compared in terms of absolute errors. A comparison between our method and two different methods of [2] and [13] are presented.

Example 4.1. Consider LFIDE equation:

$$u'(x) = xe^x + e^x - x + \int_0^1 xu(t)dt, \quad u(0) = 0, \quad (4.1)$$

with exact solution $u(x) = xe^x$. We obtain the numerical result, exact solution and absolute error at different values of $x$ which is represented in Table 1.

Table 1. The exact and approximate solution of Example 4.1

<table>
<thead>
<tr>
<th>$x$</th>
<th>Exact solution</th>
<th>FDSM</th>
<th>Abs. error</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>1.1005170917</td>
<td>1.0883647500</td>
<td>1.6806E-3</td>
</tr>
<tr>
<td>0.2</td>
<td>2.4428055161</td>
<td>2.4302253467</td>
<td>1.2580E-3</td>
</tr>
<tr>
<td>0.3</td>
<td>3.0409576427</td>
<td>3.0417429978</td>
<td>3.2146E-3</td>
</tr>
<tr>
<td>0.4</td>
<td>5.7967398791</td>
<td>5.9364062244</td>
<td>3.0893E-3</td>
</tr>
<tr>
<td>0.5</td>
<td>8.2430636555</td>
<td>8.189936476</td>
<td>5.3670E-3</td>
</tr>
<tr>
<td>0.6</td>
<td>1.093271280</td>
<td>1.0876816678</td>
<td>5.8596E-3</td>
</tr>
<tr>
<td>0.7</td>
<td>1.4096268950</td>
<td>1.401381265</td>
<td>8.2456E-3</td>
</tr>
<tr>
<td>0.8</td>
<td>1.7804327422</td>
<td>1.771521116</td>
<td>8.8806E-3</td>
</tr>
<tr>
<td>0.9</td>
<td>2.213642800</td>
<td>2.201655495</td>
<td>1.1987E-2</td>
</tr>
<tr>
<td>1</td>
<td>2.718281828</td>
<td>2.705165692</td>
<td>1.3116E-2</td>
</tr>
</tbody>
</table>

Comparing the absolute errors of Differential transform (DTrans f), parametric iteration method (PIM) and finite difference Simpson method (FDSM) of Example 4.1.

Table 2. Comparison of the absolute errors of differential transform (DTrans f), parametric iteration method (PIM) and finite difference Simpson method (FDSM) of Example 4.1

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
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<td>1.10517092E-1</td>
<td>1.6806E-3</td>
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<tr>
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<td>2.78651355E-2</td>
<td>2.44280551E-1</td>
<td>1.2580E-3</td>
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</tr>
<tr>
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<td>5.93640622E-1</td>
<td>5.3670E-3</td>
</tr>
<tr>
<td>0.5</td>
<td>9.71888952E-2</td>
<td>8.24306365E-1</td>
<td>8.8806E-3</td>
</tr>
<tr>
<td>0.6</td>
<td>1.09551714E-1</td>
<td>1.08768167E-1</td>
<td>1.1987E-2</td>
</tr>
<tr>
<td>0.7</td>
<td>1.04133232E-1</td>
<td>1.09327129E-1</td>
<td>1.3116E-2</td>
</tr>
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<td>1.94512700E-1</td>
<td>2.21364280E-0</td>
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</tr>
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<td>2.21364280E-0</td>
<td></td>
</tr>
<tr>
<td>1.0</td>
<td>1.55147712E-1</td>
<td>2.70516569E-2</td>
<td></td>
</tr>
</tbody>
</table>

In Table 2 the absolute errors obtained from DTrans f and PIM are compared with absolute error obtained from our FDSM method and the numerical results show that our method is more accurate.

Example 4.2. consider LFIDE equation:

$$u'(x) = 1 + \frac{1 - e^{x+1}}{x+1} + \int_0^1 e^tu(t)dt, \quad u(0) = 1, \quad (4.2)$$

with exact solution $u(x) = e^x$. We used maple to compute the numerical solution at different values of $x$ as shown in Table 3.

Table 3 shows the exact solution of problem in Example 4.2 and the approximate solution obtained by our method and from the absolute error obtained it indicated that our method can give good approximation of Linear Fredholm Integro-Differential Equations of second kind.

5. Conclusion

In this paper, a Finite difference-Simpson’s approach was used to solve linear Fredholm integro differential equations...


References


Table 3. The exact and approximate solution of Example 4.2

<table>
<thead>
<tr>
<th>x</th>
<th>Exact solution</th>
<th>FDSM</th>
<th>Abs. error of FDSM</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.1</td>
<td>1.105170918</td>
<td>1.081849538</td>
<td>2.33E-2</td>
</tr>
<tr>
<td>0.2</td>
<td>1.221402758</td>
<td>1.178615322</td>
<td>4.28E-2</td>
</tr>
<tr>
<td>0.3</td>
<td>1.349858808</td>
<td>1.297756098</td>
<td>5.21E-2</td>
</tr>
<tr>
<td>0.4</td>
<td>1.491824698</td>
<td>1.434534859</td>
<td>5.73E-2</td>
</tr>
<tr>
<td>0.5</td>
<td>1.648721271</td>
<td>1.596948604</td>
<td>5.17E-2</td>
</tr>
<tr>
<td>0.6</td>
<td>1.822118800</td>
<td>1.780935610</td>
<td>4.12E-2</td>
</tr>
<tr>
<td>0.7</td>
<td>2.013752707</td>
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<td>1.87E-2</td>
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<td>0.8</td>
<td>2.225540928</td>
<td>2.235618721</td>
<td>1.01E-2</td>
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<tr>
<td>0.9</td>
<td>2.459603111</td>
<td>2.512049535</td>
<td>5.24E-2</td>
</tr>
<tr>
<td>1</td>
<td>2.718281828</td>
<td>2.821429404</td>
<td>1.03E-1</td>
</tr>
</tbody>
</table>

(LFIDES). Error estimation of the scheme was derived, which show that the scheme is of second order convergence. However, the numerical results were presented in terms of absolute error and comparison was made with methods of DTransf in [2] and PIM in [13], the errors obtained showed that the derived method is good tool for approximating Linear integro-differential equation.