



α -Stable local necks of fuzzy automata

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Abstract

In this paper we introduce α -stable local necks, α -stable monogenically directable, α -stable monogenically strongly directable, α -stable monogenically trap directable, α -stable uniformly monogenically directable, α -stable uniformly monogenically strongly directable, α -stable uniformly monogenically trap-directable fuzzy automata. We have shown that α -stable local necks of fuzzy automaton exists then it is α -stable subautomaton. Further we prove a some equivalent conditions on fuzzy automaton.

Keywords

α -Stable local necks, α -Stable monogenically directable, α -Stable monogenically trap-directable, α -Stable uniformly monogenically trap-directable.

AMS Subject Classification

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1. Introduction

Fuzzy set was introduced by L. A. Zadeh in 1965 [8]. The fuzzy set is a simple mathematical tool for representing the inevitability of vagueness, uncertainty, and imprecision in everyday life. W.G. Wee extended the fuzzy idea to automata in 1967 [7]. Later, numerous academics adapted the fuzzy notion to a wide range of domains, and it has a wide range of applications. J.N. Mordeson and D. S. Malik gave a detailed account of fuzzy automata and languages in their book [6].

T. Petkovic et al. [1] discussed directable automata, monogenically directable, generalized directable using necks. T. Petkovic et al.[3] introduce and studied trap-directable, trapped automata and other related automata. Also, we refer the survey paper Directable automata and their generalizations were investigated by S. Bogdanovic et al [2]. Fur-

ther the necks and local necks of fuzzy automata were studied and discussed in [4, 5]. In this paper we introduce α -stable local necks, α -stable monogenically directable, α -stable monogenically strongly directable, α -stable monogenically trap directable, α -stable uniformly monogenically directable, α -stable uniformly monogenically strongly directable, α -stable uniformly monogenically trap-directable fuzzy automata. We have shown that α -stable local necks of fuzzy automata exists then it is α -stable subautomata. Further we prove a some equivalent conditions on fuzzy automaton.

2. Preliminaries

Definition 2.1. [6] A fuzzy automaton $S = (D, I, \psi)$, where,

D - set of states $\{d_0, d_1, d_2, \dots, d_n\}$,

I - alphabets (or) input symbols,

ψ - function from $D \times I \times D \rightarrow [0, 1]$,

The set of all words of I is denoted by I^* . The empty word is denoted by λ , and the length of each $t \in I^*$ is denoted by $|t|$.

Definition 2.2. [6] Let $S = (D, I, \psi)$ be a fuzzy automaton. The extended transition function is defined by $\psi^* : D \times I^* \times D \rightarrow [0, 1]$ and is given by

$$\psi^*(d_i, \lambda, d_j) = \begin{cases} 1 & \text{if } d_i = d_j \\ 0 & \text{if } d_i \neq d_j \end{cases}$$

$$\psi^*(d_i, tt', d_j) = \bigvee_{q_r \in D} \{ \psi^*(d_i, t, d_r) \wedge \psi(d_r, t', d_j) \}, t \in I^*, t' \in I.$$

Definition 2.3. [4] Let $S = (D, I, \psi)$ be a fuzzy automaton. Let $D' \subseteq D$. Let ψ' is the restriction of ψ and let $S' = (D', I, \psi')$. The fuzzy automaton S' is called a subautomaton of S if

(i) $\psi' : D' \times I \times D' \rightarrow [0, 1]$ and

(ii) For any $d_i \in D'$ and $\psi'(d_i, t, d_j) > 0$ for some $t \in I^*$, then $d_j \in D'$.

Definition 2.4. [6] Let $S = (D, I, \psi)$ be a fuzzy automaton. S is said to be strongly connected if for every $d_i, d_j \in D$, there exists $t \in I^*$ such that $\psi^*(d_i, t, d_j) > 0$. Equivalently, S is strongly connected if it has no proper subautomaton.

Definition 2.5. [4] Let $S = (D, I, \psi)$ be a fuzzy automaton. A state $d_j \in D$ is called a neck of S if there exists $t \in I^*$ such that $\psi^*(d_i, t, d_j) > 0$ for every $d_i \in D$.

In that case d_j is also called t -neck of S and the word t is called a directing word of S .

If S has a directing word, then we say that S is a directable fuzzy automaton.

Definition 2.6. [5] Let $S = (D, I, \psi)$ be a fuzzy automaton. If $d_i \in Q$ is called local neck of S , if it is neck of some directable subautomaton of S . The set of all local necks of S is denoted by $LN(S)$.

3. α -Stable Local Necks of Fuzzy Automata

Definition 3.1. Let $S = (D, I, \psi)$ be a fuzzy automaton. If S is said to be α -stable fuzzy automaton then $\psi(d_i, t', d_j) \geq \alpha > 0, \forall t' \in I, \alpha = \text{Fixed value in } [0, 1]$.

Definition 3.2. Let $S = (D, I, \psi)$ be a fuzzy automaton and let $d_i \in D$. The α -stable subautomaton of S generated by d_i is denoted by $\langle d_i \rangle$. It is given by $\langle d_i \rangle = \{ d_j \mid \psi^*(d_i, t, d_j) \geq \alpha > 0, t \in I^* \}$. If it exists, then it is called the α -stable least subautomaton of S containing d_i .

Definition 3.3. Let $S = (D, I, \psi)$ be a fuzzy automaton. For any non-empty $D' \subseteq D$, the α -stable subautomaton of S generated by D' is denoted by $\langle D' \rangle$ and is given by $\langle D' \rangle = \{ \{ d_j \mid \psi^*(d_i, t, d_j) \geq \alpha > 0, d_i \in D', t \in I^* \} \}$. It is called the α -stable least subautomaton of S containing D' . The α -stable least subautomaton of a fuzzy automaton S if it exists is called the α -stable kernel of S .

Definition 3.4. Let $S = (D, I, \psi)$ be a fuzzy automaton. A state $d_i \in D$ is called α -stable local neck of S if it

is α -stable neck of some α -stable directable subautomaton of S . The set of all α -stable local necks of S is denoted by $\alpha SLN(S)$.

Definition 3.5. Let $S = (D, I, \psi)$ be a fuzzy automaton. S is called α -stable monogenically directable if every monogenic subautomaton of S is α -stable directable.

Definition 3.6. Let $S = (D, I, \psi)$ be a fuzzy automaton. S is called α -stable monogenically strongly directable if every monogenic subautomaton of M is α -stable strongly directable.

Definition 3.7. Let $S = (D, I, \psi)$ be a fuzzy automaton. S is called α -stable monogenically trap-directable if every monogenic subautomaton of S has a single α -stable neck.

Definition 3.8. Let $S = (D, I, \psi)$ be a fuzzy automaton. If $t \in I^*$ is α -stable common directing word of S if t is a α -stable directing word of every monogenic subautomaton of S . The set all α -stable common directing words of S will be denoted by $\alpha SCDW(S)$. In other words, $\alpha SCDW(S) = \bigcap_{d_i \in D} \alpha SDW(\langle d_i \rangle)$.

Definition 3.9. Let $S = (D, I, \psi)$ be a fuzzy automaton. S is called α -stable uniformly monogenically directable fuzzy automaton if every monogenic subautomaton of S is α -stable directable and have atleast one β -weak common directing word.

Definition 3.10. Let $S = (D, I, \psi)$ be a fuzzy automaton. S is called α -stable uniformly monogenically strongly directable fuzzy automaton if every monogenic subautomaton of S is strongly α -stable directable and have atleast one α -stable common directing word.

Definition 3.11. Let $S = (D, I, \psi)$ be a fuzzy automaton. S is called α -stable uniformly monogenically trap directable fuzzy automaton if every monogenic subautomaton of S has a single α -stable neck and have atleast one α -stable common directing word.

4. Properties of α -Stable Local Necks of Fuzzy Automata

Theorem 4.1. Let $S = (D, I, \psi)$ be a fuzzy automaton and $d_i \in D$. Then the following conditions are equivalent:

- (i) d_i is a α -stable local neck;
- (ii) $\langle d_i \rangle$ is a strongly α -stable directable fuzzy automaton;
- (iii) for every $t' \in I^*$, there exists $t \in I^*$ such that $\psi^*(d_i, t't, d_i) \geq \alpha > 0$.

Proof. (i) \Rightarrow (ii)

Let d_i be a α -stable local neck of S . Then there exists a α -stable directable subautomaton S' of S such that $d_i \in \alpha SN(S')$. Thus $\alpha SN(S')$ is a strongly α -stable directable fuzzy automaton. Also, $\langle d_i \rangle \subseteq \alpha SN(S')$, and $\alpha SN(S')$ is strongly connected, then $\langle d_i \rangle = \alpha SN(S')$. Therefore, $\langle d_i \rangle$ is a



strongly α -stable directable fuzzy automaton.

(ii) \Rightarrow (iii)

Let $\langle d_i \rangle$ be a strongly α -stable directable fuzzy automaton. Then d_i is a t - α -stable neck of $\langle d_i \rangle$ for some $t \in I^*$. Since $\langle d_i \rangle$ is strongly α -stable directable, for every $t' \in I^*$, there exists some $d_l \in \langle d_i \rangle$ such that $\{\psi^*(d_i, t', d_l) \geq \alpha\} > 0$. Now,
 $\psi^*(d_i, t't, d_i) = \{\wedge_{d_l \in D} \{\psi^*(d_i, t', d_l), \psi^*(d_l, t, d_i)\} \geq \alpha\} > 0$.

(iii) \Rightarrow (i)

(iii) clearly shows that d_i is a t - α -stable neck of $\langle d_i \rangle$, and hence, it is a α -stable local neck of S . \square

Theorem 4.2. Let $S = (D, I, \psi)$ be a fuzzy automaton. If $\alpha SLN(S) \neq \emptyset$, then $\alpha SLN(S)$ is a α -stable subautomaton of S .

Proof. Let $d_i \in \alpha SLN(S)$ and $t \in I$. Then, the monogenic α -stable subautomaton $\langle d_i \rangle$ of S is strongly α -stable directable. Now, $\langle d_i \rangle \subseteq \langle d_l \rangle$, for some $d_l \in \langle d_i \rangle$. Since $\langle d_i \rangle$ is strongly connected, $\langle d_i \rangle = \langle d_l \rangle$. Therefore, d_l is also a α -stable local neck of S , i.e., $d_l \in \alpha SLN(S)$. Hence, $\alpha SLN(S)$ is a α -stable subautomaton of S . \square

Theorem 4.3. Let $S = (D, I, \psi)$ be a fuzzy automaton. Then the following conditions are equivalent:

- (i) Every state of D in S is a α -stable local neck;
- (ii) S is α -stable monogenically strongly directable;
- (iii) S is α -stable monogenically directable and α -stable reversible;
- (iv) S is a direct sum of α -stable strongly directable fuzzy automata;
- (v) $(\forall d_i \in D)(\exists t \in I^*)(\forall t' \in I^*)$ such that $\psi^*(d_i, t't, d_i) \geq \alpha > 0$.

Proof. (i) \Rightarrow (ii)

If every state $d_i \in D$ is a α -stable local neck of S . Then we have that for every $d_i \in D$ the α -stable monogenic subautomaton $\langle d_i \rangle$ of D in S is α -stable strongly directable. Hence, S is α -stable monogenically strongly directable.

(ii) \Rightarrow (iii)

If S is α -stable monogenically strongly directable, then it is α -stable monogenically directable. Now, every α -stable monogenic subautomaton of S is strongly connected, hence S is α -stable reversible.

(iii) \Rightarrow (iv)

If S is α -stable reversible, then it is a direct sum of α -stable strongly connected fuzzy automata $S_\beta, \beta \in Y$. Let $\beta \in Y$ and $d_i \in D_\beta$. Then $\langle d_i \rangle = S_\beta$. Since S_β is strongly connected, and by the α -stable monogenic directability of S we have that $S_\beta = \langle d_i \rangle$ is α -stable directable. Therefore, S_β is α -stable strongly directable, for any $\beta \in Y$.

(iv) \Rightarrow (i)

Let S be a direct sum of α -stable strongly directable fuzzy automata $S_\beta, \beta \in Y$. Then for each state $d_i \in D$, there exists $\beta \in Y$ such that $d_i \in D_\beta$, that is, $d_i \in S_\beta = \alpha SN(S_\beta)$, so d_i is a α -stable local neck of S .

(i) \Rightarrow (v)

Since, every state of S is a α -stable local neck, for any $d_i \in D, \langle d_i \rangle$ is α -stable monogenically strongly directable. Hence, $\langle d_i \rangle$ is α -stable reversible.

(v) \Rightarrow (i)

This is an immediate consequence of proof of the Theorem 4.1. \square

5. Conclusion

We introduce α -stable local necks, α -stable monogenically directable, α -stable monogenically strongly directable, α -stable monogenically trap-directable, α -stable uniformly monogenically directable, α -stable uniformly monogenically strongly directable, α -stable uniformly monogenically trap-directable fuzzy automata. We have shown that α -stable local necks of fuzzy automata exists then it is α -stable subautomata. Further we prove a some equivalent conditions on fuzzy automaton.

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